1	RADIO WAVE ABSORBER	26 C	.Mounted on ship (EPO)
2	.For aircraft or missile	26 D	.Ground based (EPO)
3	.For camouflage	27	PRESENCE DETECTION ONLY
4	.With particular geometric	28	.By motion detection
	configuration	29	AIRCRAFT COLLISION AVOIDANCE
5	RADAR REFLECTOR		SYSTEM (CAS)
6	.With modulation	30	.With transponder
7	.Corner	31	Including synchronized clock
8	Inflatable or collapsable	32	Included in Secondary
9	Decoy or tow target		Surveilance Radar (SSR) or Air
10	.Inflatable or collapsable		Traffic Control Radio Beacon
11	.With spherical lens (e.g.,		System (ATCRBS)
	Luneberg lens)	33	AIRCRAFT LANDING SYSTEM
12	.Chaff	34	.Ground control approach (GCA)
13	RADAR EW (ELECTRONIC WARFARE)	35	.Microwave landing system (MLS)
14	.ECM (Electronic countermeasures,	36	AIR TRAFFIC CONTROL
	i.e., jamming)	37	.Secondary Surveilance Radar
15	With repeater		(SSR) or Air Traffic Control
16	.ECCM (Electronic counter-		Radar Beacon System (ATCRBS)
	countermeasures, i.e.,	38	With altitude information
	antijamming)	39	With side lobe suppression
17	Radar reacts to jamming	40	With defruiting or degarbling
18	By changing frequency	41	SHIP COLLISION AVOIDANCE
19	By varying gain or blocking	42	RADAR TRANSPONDER SYSTEM
	receiver	43	.Combined with primary radar
20	.Detection of surveilance		system
21	BASE BAND SYSTEM	44	.Unique identity
22	TRANSMISSION THROUGH MEDIA OTHER	45	.IFF or SIF
	THAN AIR OR FREE SPACE	46	.Navigational
23	BERTHING OR DOCKING	47	Distance measuring equipment
24	BLIND AID		(DME)
25 R	SYNTHETIC APERTURE RADAR	48	With automatic lock-on
25 A	.Mapping or imaging using	49	With VOR/TACAN
	synthetic aperture radar (EPO)	50	.With Telemetry
25 B	Specially adapted for moving	51	.Radar transponder only
	target detection (EPO)	52	COMBINED WITH DIVERSE TYPE
25 C	Combined with monopulse or		RADIANT ENERGY SYSTEM
	interferometric (EPO)	53	.With infrared device
25 D	With frequency domain	54	.With laser
	processing of the SAR signals	55	.With television
	in azimuth (EPO)	56	.With direction finding
25 E	With time domain processing of	57	.With radio voice communication
	the SAR signals in azimuth,	58	.With transmission to a remote
	e.g. time focusing (EPO)		station
25 F	Particular SAR processing	59	PLURAL RADAR
	techniques (e.g., squint mode,	60	TRANSMITTING INTELLIGENCE
	doppler beam-sharpening mode,	61	RETURN SIGNAL CONTROLS EXTERNAL
	spotlight mode, bistatic SAR,		DEVICE
	inverse SAR) (EPO)	62	.Missile or spacecraft guidance
26 R	RADAR FOR METEOROLOGICAL USE	63	.Aircraft guidance
	(EPO)	64	With map matching
26 A	.Mounted on satellite (EPO)	65	With terrain avoidance or alarm
26 B	.Mounted on aircraft (EPO)	66	.Camera

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67	.Gun (e.g., fire control)	107	.Combined with determining
68	.Proximity fuze		distance and direction
69	.Device actuated by presence of	108	With correlation
	land vehicle	109	.Combined with determining
70	.Radar mounted on and controls		distance
	land vehicle	110	With plural fixed range gates
71	With control of brakes or	111	With plural receiver frequency
	steering		band separation
72	With control of safety device	112	With plural frequencies
7 2	(e.g., air bags)	112	transmission
72		113	
73	RETURN SIGNAL CONTROLS RADAR	113	.Combined with determining
5 4	SYSTEM	7.7.4	direction (i.e., bearing)
74	.Antenna control	114	.Combined with determining sense
75	Physical orientation		of motion (i.e., approaching
76	With ground tracking		or receding)
77	With signal error correction	115	.Digital
78	Conical scan	116	.With plural received frequency
79	Lobe switching		band separation
80	Monopulse	117	.With plural beams (e.g.,
81	Beam direction by phase or		"Janus")
-	frequency control	118	DETERMINING DISTANCE
82	.Transmitter	119	.Miss distance indicator (MDI)
83	Signal phase or frequency other	120	.Altimeter
03	than pulse repetition	121	With additional indicator
	frequency (PRF)	122	FM type
84		123	.Height finder
_	Function of doppler frequency	123	_
85	Function of distance		.Material level within container
86	With constant phase	125	.With remote cooperating station
87	With constant beat frequency	126	.Triangulation
88	Transmission timing (e.g., ring	127	.Phase comparison
	around)	128	.With frequency modulation
89	.Receiver	129	Plural frequencies transmitted
90	Automatic target detection	130	Plural modulation
91	Gain or threshold	131	Combined with pulse modulation
92	Automatic gain control (AGC)		(e.g., frequency agile)
93	Constant false alarm rate	132	With pulse modulation (e.g.,
	(CFAR)		"Chirp")
94	Gating	133	Combined with determining
95	Automatic range tracking		direction
96	Automatic track while scan	134	.With pulse modulation
90	(ATWS)	135	Digital (e.g., with counter)
97			_
	With automatic lock-on	136	With plural fixed range gates
98	Frequency	137	With variable pulse repetition
99	Doppler frequency tracking		frequency (PRF) or pulse width
100	Wtih local osillator control	138	With type "A" or "J" range
101	With filter control		scope
102	Phase	139	Combined with determining
103	Phase locked loop		direction
103	Fliase Tocked Toop		
104	DETERMINING VELOCITY	140	With azimuth and elevation
	DETERMINING VELOCITY	140	With azimuth and elevation determination
104	-	140 141	
104 105	DETERMINING VELOCITY Other than doppler (e.g., range rate)		determinationOff boresight
104	DETERMINING VELOCITY Other than doppler (e.g., range	141	determination

144	PPI type	191	Mapping
145	.With correlation	192	.Spectrum analysis
146	.Combined with determining	193	Harmonic
	direction	194	.Complex signal (in phase and
147	DETERMINING DIRECTION		quadrature)
148	.Low angle processing	195	.Digital processing
149	.Monopulse	196	Fast fourier transform (FFT)
150	With common IF channel	197	With video quantizer
151	With channel equalization	198	.For receiver protection
152	With quadrature difference processing	199	.Automatic frequency control (AFC)
153	With particular antenna or	200	.For frequency modulation
	waveguide	201	Combined with pulse modulation
154	Combined with beam steering	202	.For pulse modulation
155	.Lobe switching	203	With noise reduction
156	.Interferometer	204	With pulse shaping
157	.With frequency or phase steering	205	.Sensitivity time control (STC)
158	.Scanning	350	DIRECTIVE
159	CLUTTER ELIMINATION	351	.Including a radiometer
160	.MTI (Moving target indicator)	352	.Including a satellite
161	With vehicle movement	353	Having a signal repeater
	compensation (e.g., AMTI	354	With beam steering
	(Airborn MTI))	355	With control of satellite
162	Digital		altitude
163	With blind speed elimination	356	Synchronous satellite
164	With storage tube	357.01	With position indicating
165	TESTING OR CALIBRATING OF RADAR	357.02	With accuracy enhancing
	SYSTEM	357.02	Using differential correction
166	.Proximity fuze	357.03	With ambiguity resolving
167	.With laser	357.05	Using Doppler frequency shift
168	.With noise generation	357.05	Using Global Positioning
169	.By simulation	337.00	Satellite (GPS or Glonass)
170	Microwave	357.07	Tracking or monitoring (i.e.,
171	Doppler	337.07	lost or stolen vehicles)
172	With delay	357.08	Determining relative position
173	with delay .By monitoring	337.00	(e.g., distance or direction)
174	Calibrating	357.09	With transmission of
175	WITH PARTICULAR CIRCUIT	337.09	location-indicative
176			information to or from a
177	.Display		remote station
178	Plural	357.1	Combined with
179	Projection type	337.1	telecommunication
	Image production	357.11	Attitude determination
180	Stereoscopic or tridimensional	357.11	GPS receiver signal
181	Color	337.12	processing
182	Electronic marker generation	357.13	_
183	Cursor	357.13	With storage device (i.e., map or database)
184	<pre>With stabilization (e.g., True Motion, True North)</pre>	357.14	Combined with secondary
185	Scan conversion		navigation system (i.e.,
186	With sweep expansion		LORAN, gyroscope, inertial,
187	.Augmenter	255 45	dead reckoning, etc.)
188	.With polarization	357.15	Satellite selection (i.e.,
189	.For correlation	255 45	tracking or acquisition)
190	.With recording	357.16	Using low Earth orbit (telecommunication) satellites

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357.17	With postigular action taken	396	Omaga
337.17	With particular action taken responsive to position	390	Omega Decca
358	With satellite signal	398	Rotating beacon signal
330	correction	399	Tacan
359	.Including antenna orientation	400	Receiver only
360	.Including antenna pattern	401	VOR
300	plotting	402	Doppler
361	.Including polarized signal	403	With circular array of
331	communication transmitter or	105	antennas
	receiver	404	VOR
362	Receiver only	405	Doppler
363	Circular	406	With circular array of
364	Eliptical	100	antennas
365	Circular	407	Fixed course or bearing
366	Eliptical	107	indicating
367	.Including directive	408	Moving beam
	communication system	409	With superimposed images
368	.Including a steerable array	410	Glide slope transmitter or
369	Injection radiation type	110	receiver
370	Retrodirective	411	Receiver only
371	With electronic scanning	412	Transmitter oly
372	Controlled	413	Localizer transmitter or
373	With a matrix		receiver
374	With a switch	414	Distinctive frequencies equi-
375	With a delay line (e.g.,		signal type
	serpentine transmission line,	415	Coded equi-signal (e.g., A
	frequency scanning)		and N type)
376	Including a remote energy	416	Sequentially effective
	source		reflectors
377	Including a computer	417	Direction-finding receiver only
378	.Utilizing correlation techniques	418	Doppler
379	Side lobe elimination	419	Portable
380	Sum of each antenna channel	420	With error or deviatioan
	signal		compensator or eliminator
381	Difference of each antenna	421	Pulse-type noise elimination
	channel signal		or compensation (e.g., sky
382	Mixing each antenna channel		waves)
	signal	422	With self-orienting antenna
383	Sum of each antenna signal		pattern
384	Difference of each antenna	423	Plural antennas
	channel signal	424	Tracking interferometer
385	.Beacon or receiver	425	Conical scan antenna type
386	With transmisson of bearing or	426	Step track antenna type
	position determinative signals	427	Monopulse or pseuodo
387	Iso-chronic type		monopulse tracking antenna
388	Loran		type
389	Loran-C	428	With continuously movable
390	With cycle selection		antenna pattern
391	Loran-A	429	Including a stationary
392	With automatic gain control		antenna
393	Iso-frequency type	430	Including plural moving
394	Iso-phase type	405	antennas
395	With hetrodyne	431	Including a goniometer
	synchronization	432	With plural fixed antenna
			pattern comparing

433	Successively commutated	Any foreign patents or non-patent litera-
434	Including more than two antennas	ture from subclasses that have been reclassified have been transferred
435	By diode switching	directly to FOR Collections listed below.
436	By modulation	These Collections contain ONLY foreign
437	Including more than two	patents or non-patent literature. The par-
	antennas	enthetical references in the Collection titles refer to the abolished subclasses
438	Including separate indicators	from which these Collections were derived.
439	<pre>Including combined effect indicator</pre>	115m which chebe collections were delived.
440	Including a goniometer	
441	Having a goniometer	
442	Having a phase detector	
443	Having a direction indicator	
444	Having plural receivers	
445	Having more than two antennas	
446	Unequal distance between at least three antennas	
447	Having a spiral antennas	
448	Having a coil or loop type	
449	Having a moving antenna	
450	naving a moving antenna .Position indicating (e.g.,	
400	triangulation)	
451	By computer	
452	By plotting table	
453	By deflected or repeated signal	
454	Traffic	
455	Having collision avoidance	
456	Having traffic control	
457	Land vehicle location (e.g.,	
13 /	bus, police car	
458	Distance	
459	Underground object location	
460	Storm or atomic explosion	
461	With speed determination	
462	With altitude determination	
463	Having plural transmitters or	
	receivers	
464	Plural transmitters only	
465	Plural receivers only	
	-	

FOREIGN ART COLLECTIONS

FOR 000 CLASS-RELATED FOREIGN DOCUMENTS

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